Run manipulator to grab/choke up on piece (while held)

Score piece (eject manipulator)

Intake reverse motor?



Up: Prep for get cone

Down: Prep for get cube

Left: Load Piece Conveyor

Right: Elevator loading station

Stop motors

Elevator bottom position

Score low position

Score mid position

Score high position

Manual wrist  
(X-axis)

(hold) Manual elevator/ wrist enable

Manual elevator (X-axis)



Intake in

Intake out

Move to

Scoring position

Calibrate forward